

# The Doppler Lidar Boundary-Layer Turbulence Statistics Value-Added Product (aka the BLTS VAP)

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**ARM**

CLIMATE RESEARCH FACILITY



**Pacific Northwest**  
NATIONAL LABORATORY

*Proudly Operated by Battelle Since 1965*

# Background and Goals

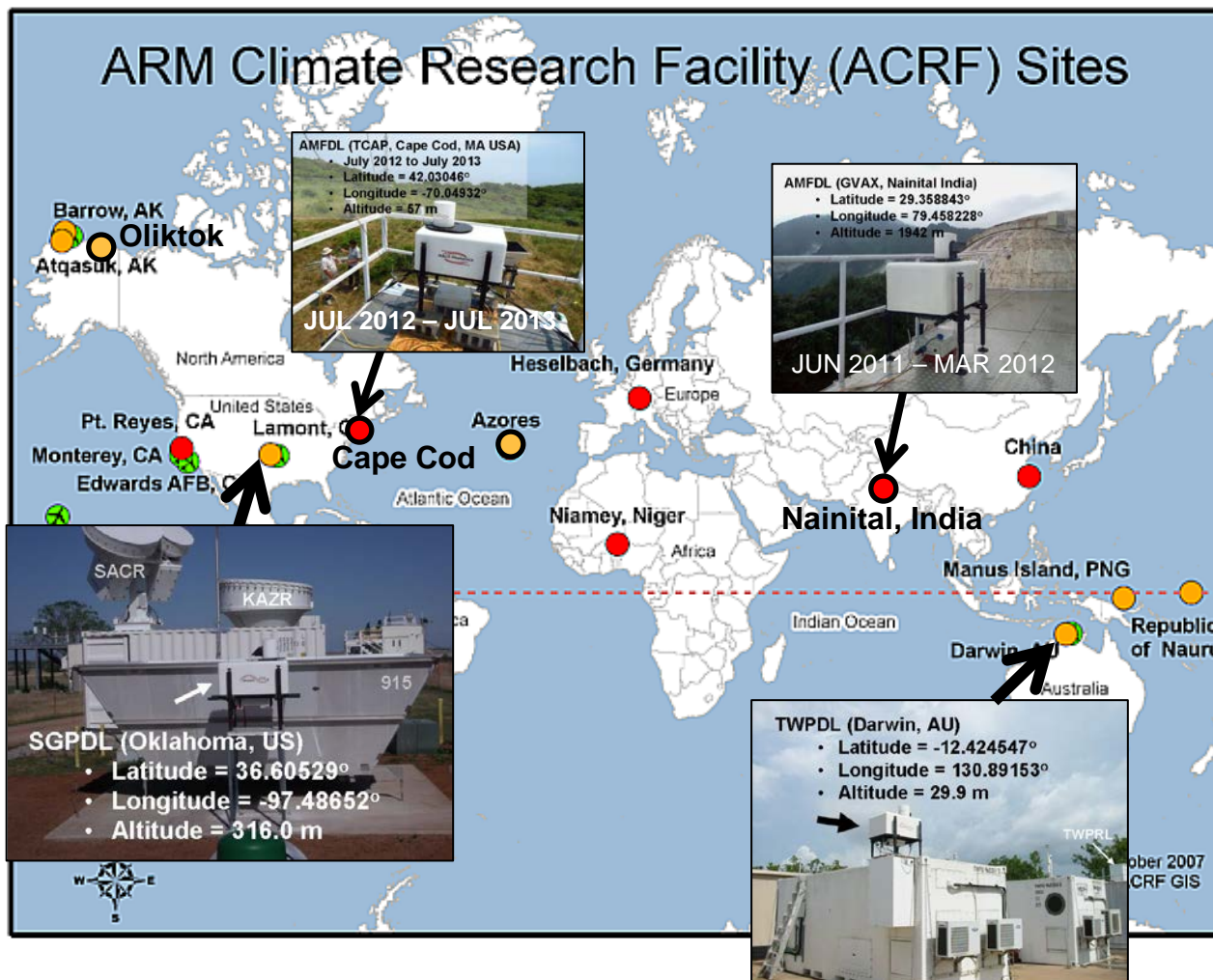
- ▶ Doppler lidars (DLs) were recently added to the suite of ARM instrumentation in order to fill a long-standing measurement gap, i.e. vertical velocities in clear-air and sub-cloud layers. These measurements are important for ...
  - Understanding mixing processes
  - Understanding cloud lifecycles
  - Development and validation of parameterization scheme in models
- ▶ The ARM DLs provide height and time resolved measurements of vertical velocity (and aerosol backscatter)
- ▶ The Boundary-Layer Turbulence Statistics (BLTS) VAP uses data from the DLs and other instruments to provide estimates of
  - Clear-air boundary-layer vertical velocity statistics
  - Cloud properties

# ARM Doppler Lidars

- Manufacturer: Halo Photonics (UK)
- Specs
  - Wavelength: 1.5  $\mu\text{m}$
  - Pulse width: 150ns (22.5m)
  - Pulse Energy:  $\sim 100 \mu\text{J}$
  - Pulse repetition Frequency: 15 kHz
  - Max Measurement Range: 10 km
  - Typical range:  $\sim 2\text{-}4 \text{ km}$
  - Velocity precision:  $\sim 10 \text{ cm s}^{-1}$
- Full upper hemispheric scanning capability
- Sensitive to aerosol backscatter
- Measurements:
  - Radial Velocity
  - Attenuated aerosol backscatter



# Deployment Locations



## Currently 3 systems

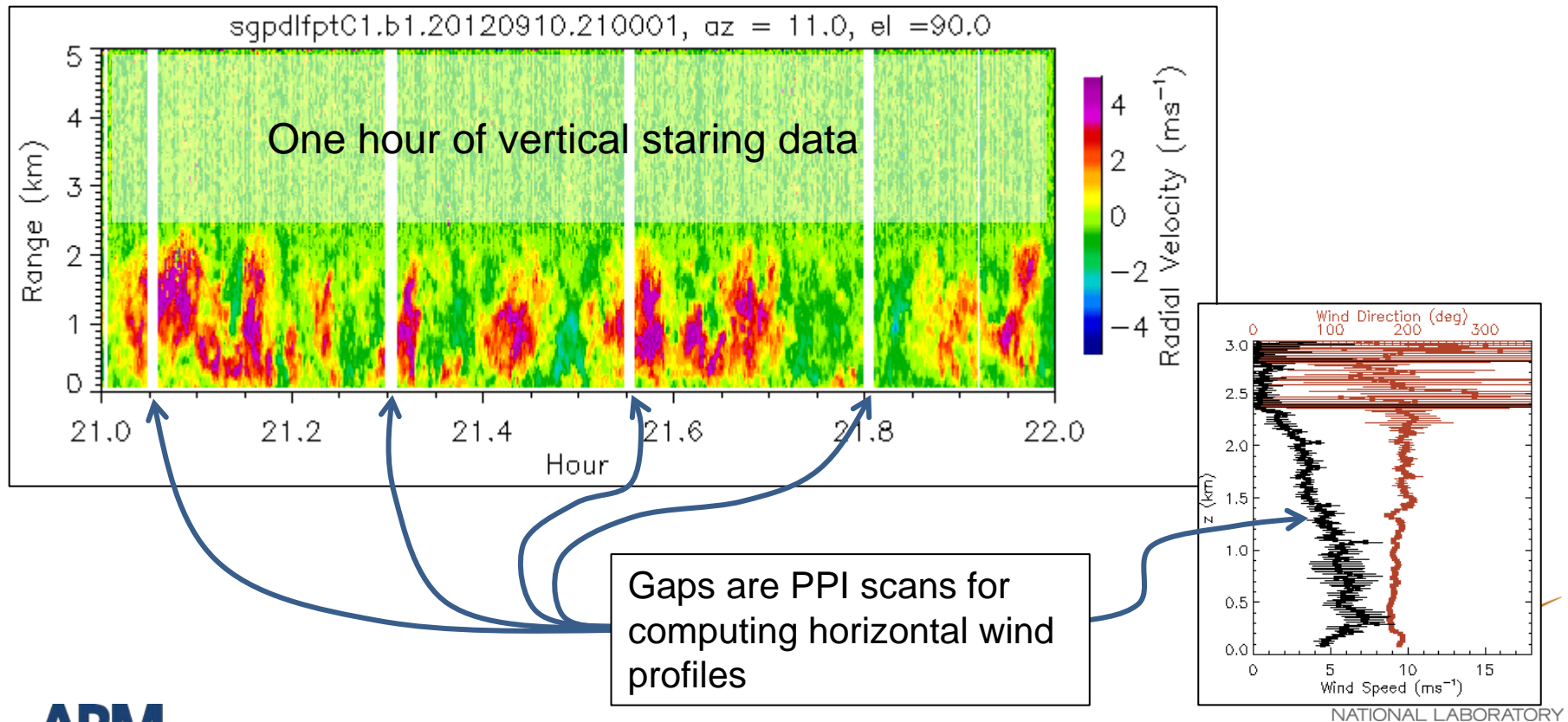
- Fixed Sites (2)
  - Southern Great Plains
  - Tropical Western Pacific – Darwin
- Mobile Facility (1)
  - GVAX (June 2011 to March 2012)
  - TCAP (July 2012 to July 2013)

## Future

- Oliktok AK (1)
- Azores (1)

# Operational Configuration for the ARM Doppler Lidars

- ▶ Vertical stare most of the time
- ▶ PPI scan once every 15 minutes (~40 seconds per scan)
- ▶ 30 m range gate, 1 second pulse integration time
- ▶ Duty cycle = ~82% → 1 profile per 1.22 seconds



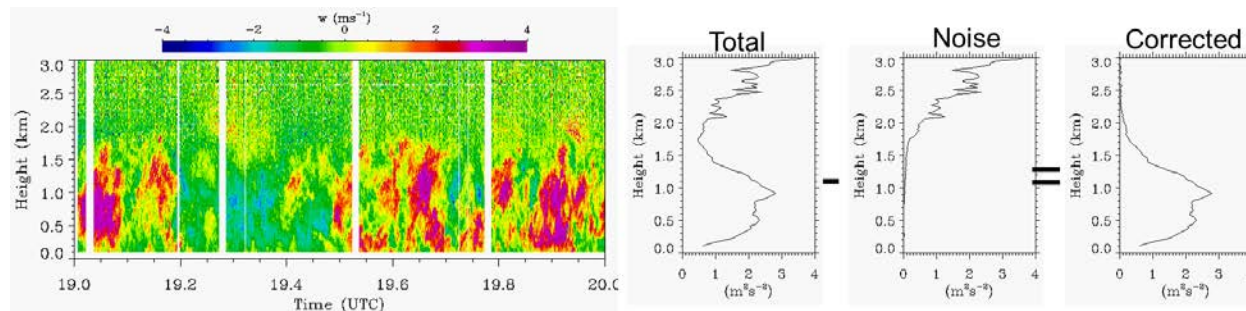
# BLTS VAP Output

- ▶ Daily files, 30-minute average, 30m vertical resolution
- ▶ DL-derived quantities
  - Profiles (clear-air) of w stats from 100m to 4 km AGL
    - median w
    - Updraft fraction
    - Moments: Variance, Skewness, Kurtosis
    - Dissipation rate
  - Profiles of median SNR from 100m to 4km AGL
  - Profiles of horizontal winds resampled from DL VAD VAP
  - Cloud properties from 100m to 9.6 km AGL
    - Cloud base height (CBH)
    - Cloud fraction
    - Cloud base w stats
      - ◆ Median
      - ◆ Updraft fraction
- ▶ Quantities derived from other instruments
  - Surface fluxes (ECOR) and met
  - Precipitation Flag
  - CBH from ceilometer

# Dealing with Noise

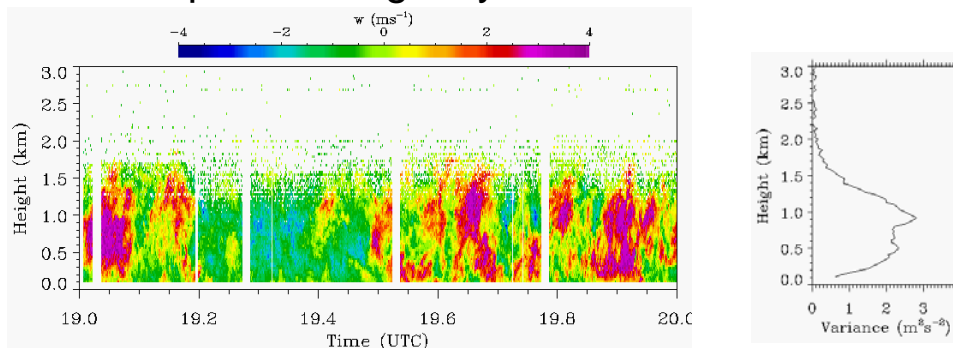
## ► Noise compensation technique

- Lenschow, Wulfmeyer, Senff, 2000: Measuring Second- through Fourth-Order Moments in Noisy Data, *JTECH*, **17**, 1330-1347.
- Noise variance is estimated from time series analysis
  - Frequency domain
  - Time domain
- Atmospheric variance = (Uncorrected variance) – (noise variance)



## ► SNR threshold technique

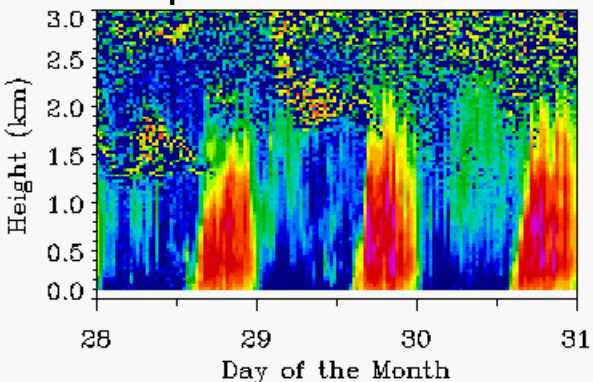
- Statistics are computed using only radial velocities above a prescribed SNR threshold.



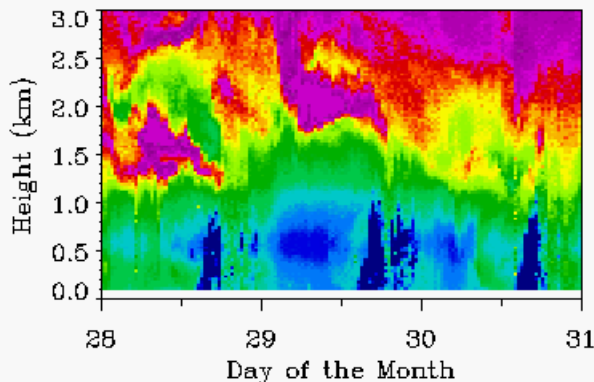
# Noise Variance for Quality Control

- ▶ The noise variance is used as a quality control field
  - Threshold set at  $1 \text{ m}^2\text{s}^{-2}$

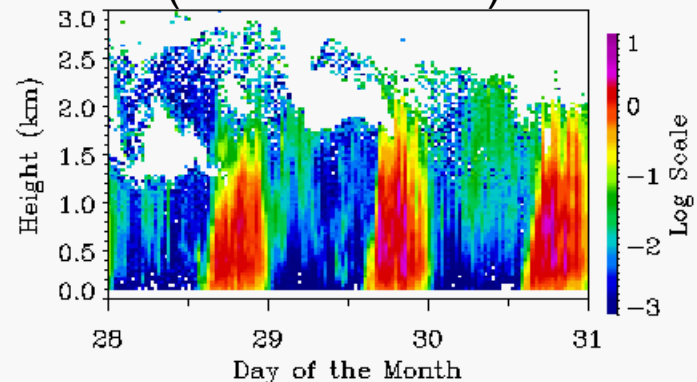
Unfiltered noise-compensated variance



Noise variance

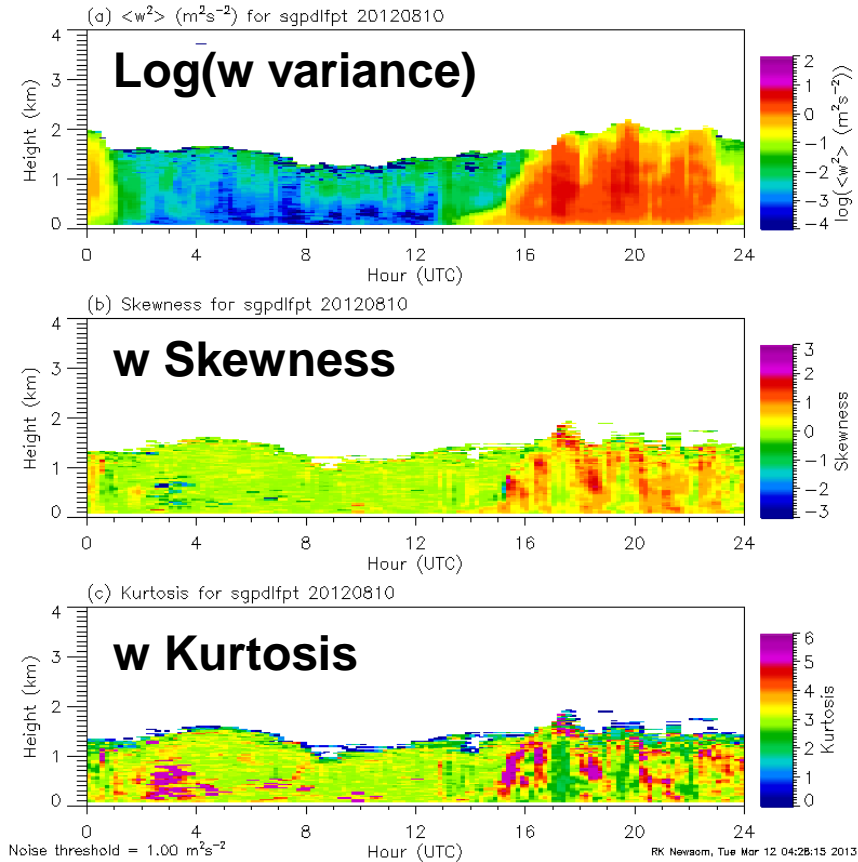


Filtered noise-compensated variance  
(noise  $< 1 \text{ m}^2\text{s}^{-2}$ )

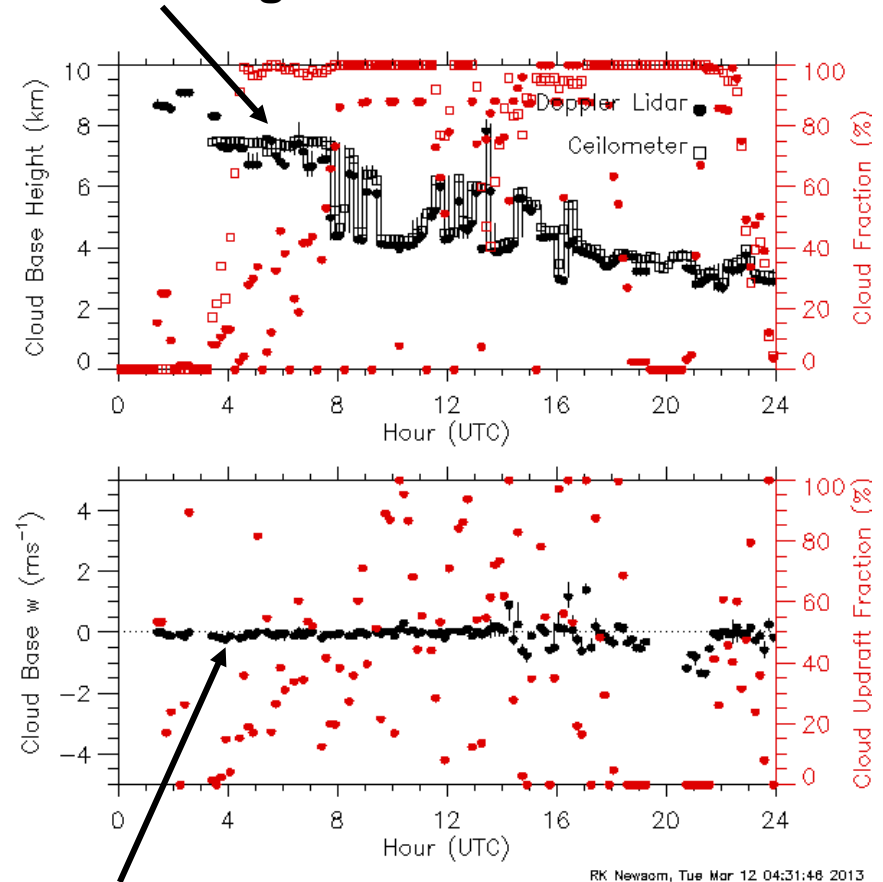




# BLTS Sample Quicklooks

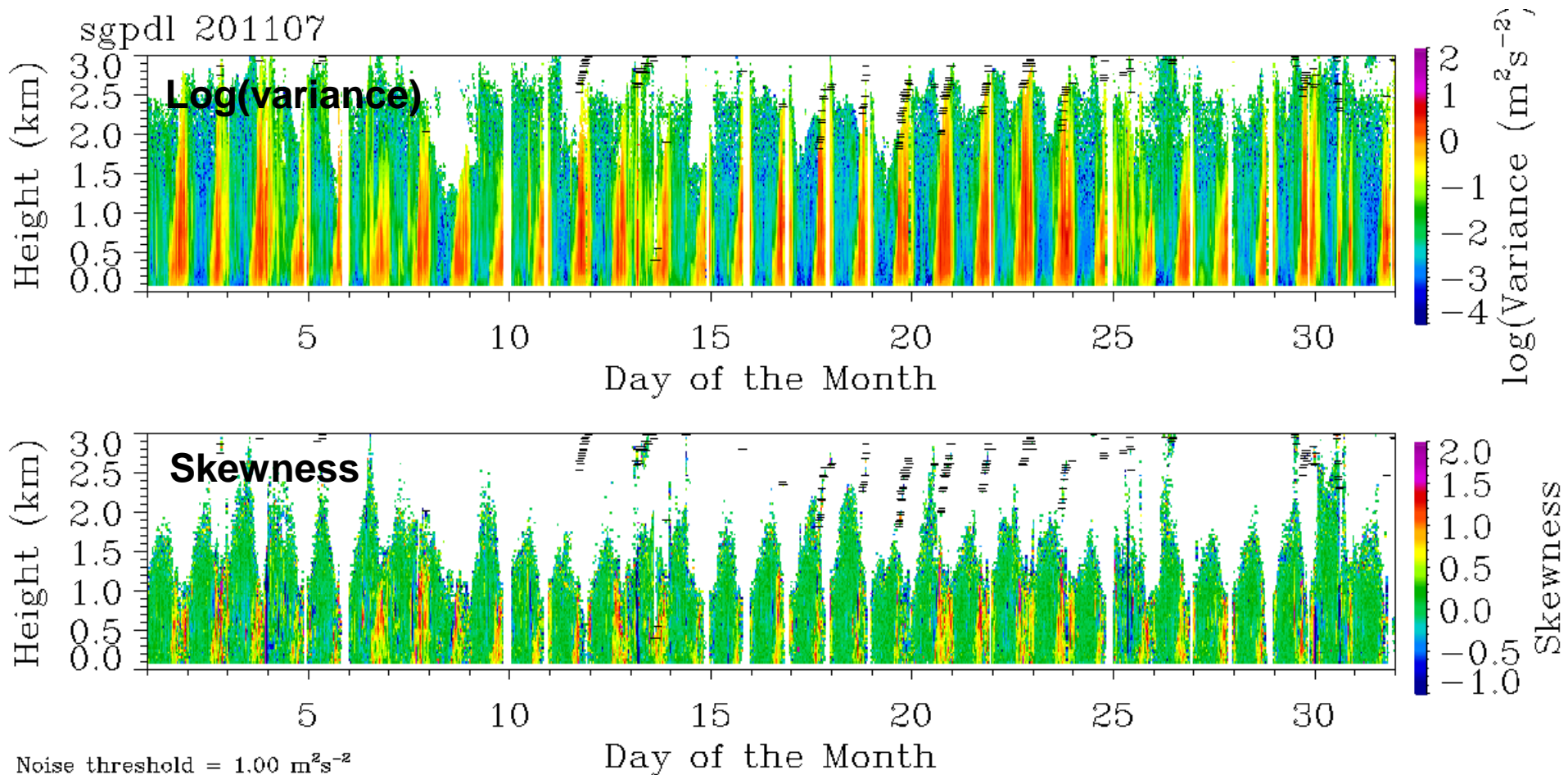


## Cloud Base Heights



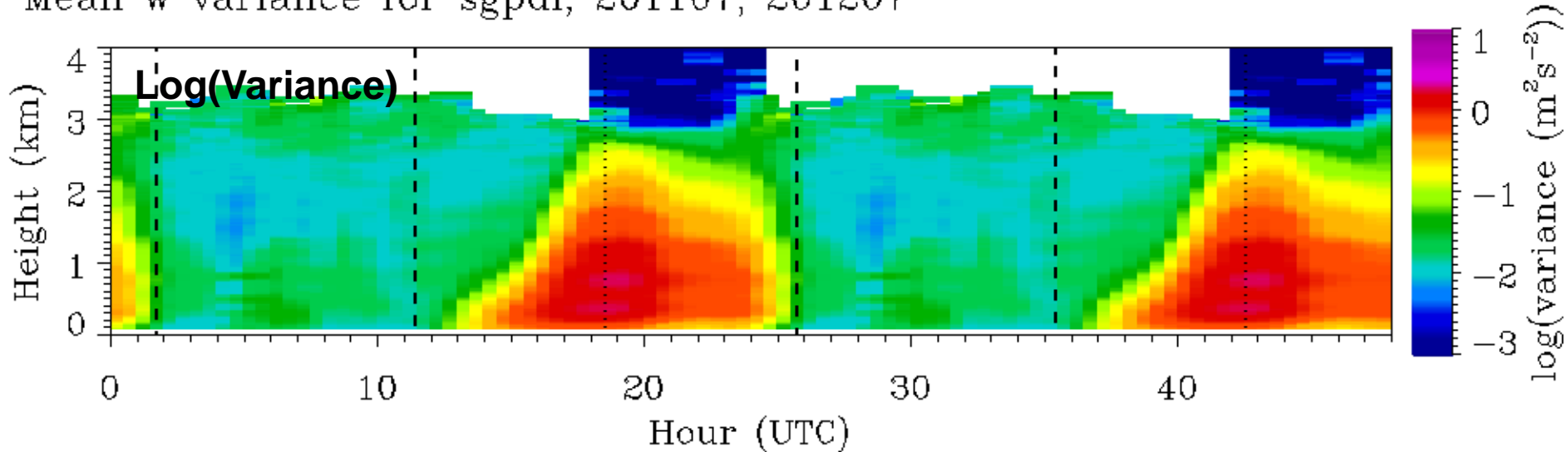
## Cloud Base $w$

# Variance and Skewness at SGP During July 2011

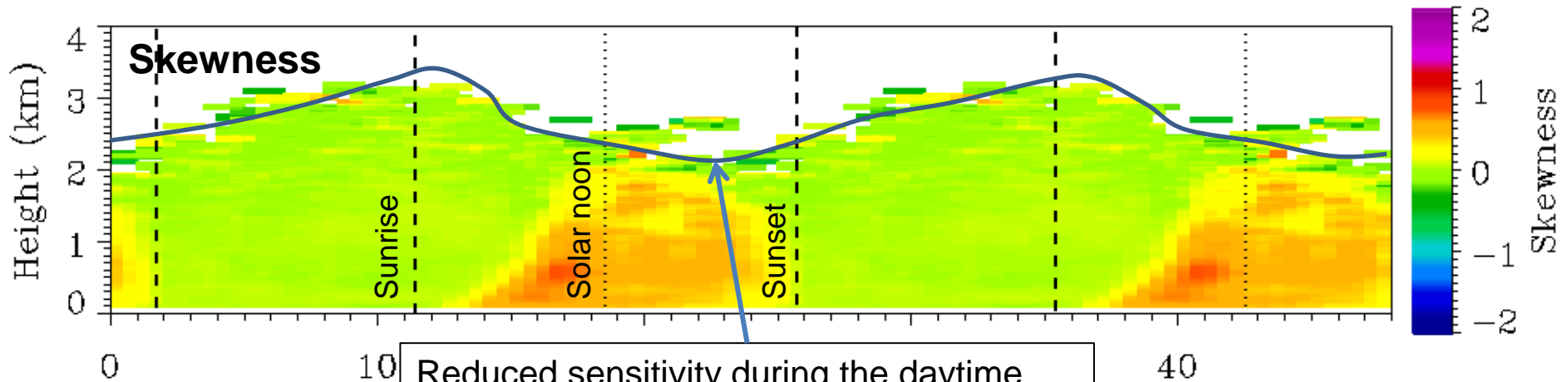


# Mean Diurnal Variance and Skewness at SGP for July 2012 and July 2011

Mean w variance for sgpdl, 201107, 201207



Mean w skewness for sgpdl, 201107, 201207



Reduced sensitivity during the daytime due to refractive turbulence

Noise threshold =  $1.00 \text{ m}^2\text{s}^{-2}$

# Future Work

- ▶ BLTS VAP is currently under development. Most of the development effort is complete.
- ▶ Still need to finalize the Data Object Design (DOD), and create QC flags for each of the primary output variables.
- ▶ As of March 2013, the release data is TBD; however, preliminary results can be viewed at <https://engineering.arm.gov/~newsom/>