







## HSRL-Radar particle size measurement

For droplets which are small compared to the radar wavelength but large compared to the lidar wavelength:

Radar scattering cross section =  $\beta_{radar} \sim \langle V^2 \rangle \sim \langle D^6 \rangle$  ------ Rayleigh scattering Lidar extinction cross section =  $\beta_{lidar} \sim \langle A \rangle \sim \langle D^2 \rangle$  ------ Geometric optics

Where:

<V<sup>2</sup>> = average volume squared of the particles <A> = average projected area of the particles

We can define:

$$D'_{eff} = \lambda \cdot \left(\frac{2.0}{\pi^3 \cdot k_w^2}\right)^{0.25} \cdot \left(\frac{\beta_{bsRadar}}{\beta_{extLidar}}\right)^{0.25}$$

Where:

$$\lambda_{radar}$$
 = radar wavelength  
 $k_w$  = dielectric constant of water

Where: 
$$\beta_{bsRadar}(\frac{1}{m \cdot sr}) = \frac{3}{8\pi}(\frac{1}{sr}) \cdot \beta_{scat}(\frac{1}{m})$$

The extinction cross section,  $\beta_e$ , can be derived from the molecular return by taking the logarithm and then differentiating with respect to range, r:

$$S_m(r) \sim \eta(r) \cdot \frac{1}{r^2} \cdot \frac{3}{8\pi} \cdot \beta_m(r) \cdot e^{-2\int_0^r \beta_e(r)dr}$$

Taking the logarithm and differentiating with respect to range Provides the extinction cross section in terms of  $S_m$  and  $\beta_m$ :

$$\beta_e(r) = \frac{1}{2} \cdot \frac{d}{dr} \left[ log(\frac{\eta(r) \cdot \beta_m(r)}{r^2 \cdot S_m(r)}) \right]$$

Unfortunately, the geometric correction,  $\eta(r)$ , does not cancel out:





The HSRL provides robustly calibrated retrievals of the backscatter cross section. Thus given a value for the backscatter phase function we can derive the extinction cross section from:

$$\beta_{ext} = \beta_{bs} \cdot \frac{4\pi}{P(180)}$$

In the past we used a constant value,  $\frac{P(180)}{4\pi} = 0.065$ , derived from direct multiple scattering corrected HSRL extinction measurements in drizzle.



Assuming a gamma distribution of particle diameters:

$$N = a \int_0^\infty D^\alpha \cdot exp(-\frac{\alpha}{\gamma} \cdot (\frac{D}{D_m})^\gamma) \cdot dD$$

Where:

N = number of particles

D = particlle Diameter

 $D_m$ = mode diameter

The effective diameter prime can be written as:

$$D'_{eff} = \frac{\int D^{\alpha+6} \cdot exp(-\frac{\alpha}{\gamma} \cdot \frac{D}{D_m}^{\gamma}) \cdot dD}{\int D^{\alpha+2} \cdot exp(-\frac{\alpha}{\gamma} \cdot \frac{D}{D_m}^{\gamma}) \cdot dD} = \frac{\frac{\alpha}{\gamma} \cdot \frac{1}{\gamma} \cdot D_m \cdot \Gamma(\frac{\alpha+7}{\gamma})}{\Gamma(\frac{\alpha+3}{\gamma})}$$

Solving for the mode diameter, D<sub>m</sub>:

$$D_m = D'_{eff} \cdot \left(\frac{\alpha}{\gamma}\right)^{\frac{1}{\gamma}} \cdot \left(\frac{\Gamma(\frac{\alpha+3}{\gamma})}{\Gamma(\frac{\alpha+7}{\gamma})}\right)^{\frac{1}{4}}$$

Backscatter phase function for drizzle from Mie theory



## Backscatter phase function vs size parameter averaged over $\delta x = 1$ intervals.

Backscatter phase function vs mode diameter after smoothing over gamma distribution of particles sizes,  $\lambda = 532$ nm.

Gamma distribution:

$$N = a \int_0^\infty D^\alpha \cdot exp(-\frac{\alpha}{\gamma} \cdot (\frac{D}{D_m})^\gamma) \cdot dD$$

Non- Rayleigh correction to radar backscatter







Non-Rayleigh radar adjustment, dist( $\alpha_w = 1.0, \gamma_w = 1.0$ ) 27-Jul-2013.00

The radar weighted fall velocity, <V<sub>rf</sub>>:

$$< V_{rf} >= \frac{\int V_f \cdot D^{\alpha+6} \cdot exp(-\frac{\alpha}{\gamma} \cdot \frac{D}{D_m}^{\gamma}) \cdot dD}{\int D^{\alpha+6} \cdot exp(-\frac{\alpha}{\gamma} \cdot \frac{D}{D_m}^{\gamma}) \cdot dD}$$

And the mass weighted fall velocity, <V<sub>mf</sub>>:

$$< V_{mf} >= \frac{\int V_f \cdot D^{\alpha+3} \cdot exp(-\frac{\alpha}{\gamma} \cdot \frac{D}{D_m}^{\gamma}) \cdot dD}{\int D^{\alpha+3} \cdot exp(-\frac{\alpha}{\gamma} \cdot \frac{D}{D_m}^{\gamma}) \cdot dD}$$

Where the fall velocity,  $V_f$  , is computed from:

$$V_f = \frac{\eta}{\rho_{air}D} \left(\frac{\delta_0^2}{4} \left[ \left(1 + C_1 X^{\frac{1}{2}}\right)^{\frac{1}{2}} - 1 \right]^2 - a_0 X^{b_0} \right)$$

Khovostyanov and Curry, JAS May 2005, Vol 62

And the Beard Number, X expressed in terms of particle area, volume and density along with the acceleration of gravity, air density, particle diameter and the dynamic viscosity:

$$X = \frac{2 \cdot volume \cdot \rho_{particle} \cdot \rho_{air} \cdot g \cdot D^2}{area \cdot \eta^2}$$















## $rac{eta_{bsRadar}}{eta_{bsLidar}} = vs = D_{mode}$ from Mie theory using gamma distribution









