

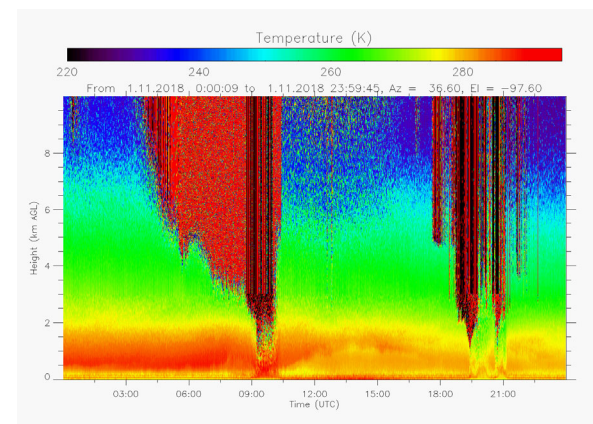
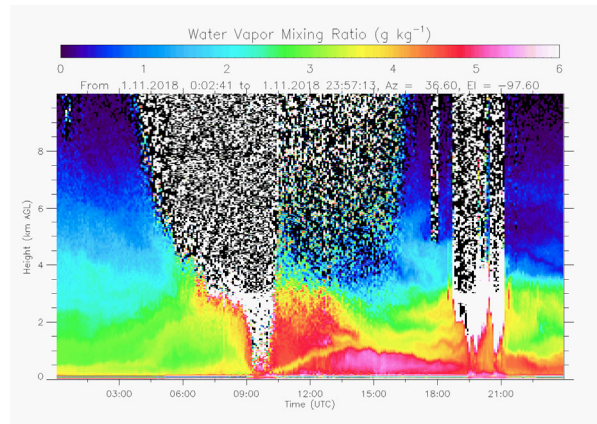
Compact Automatic Rotational Raman Lidar System for Continuous Day- and Nighttime Temperature and Humidity measurements

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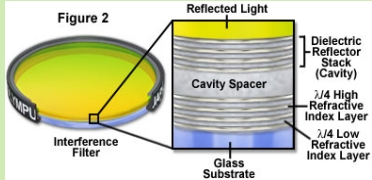
<https://www.ufz.de/moses>

Helmholtz Centre for
Environmental Research (UFZ)

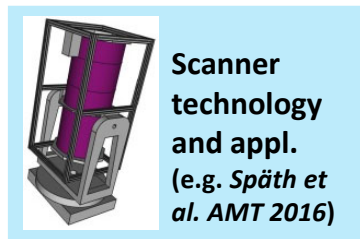


Severe gaps in the observation of thermodynamic profiles must be closed in order to advance our understanding of Earth system processes (*Wulfmeyer et al. Rev. Geophys. 2015*).

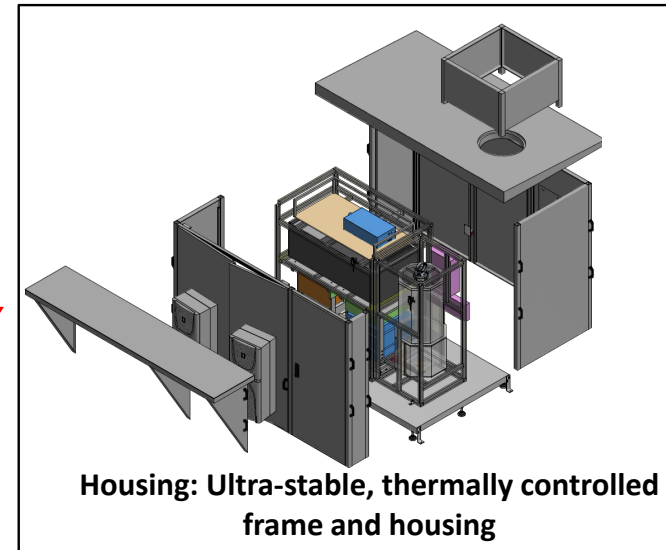
WV and T Raman lidar for MOSES



Interference filters:
Narrow-band, high transmission, side-band suppression
(e.g. Hammann et al. ACP 2015)



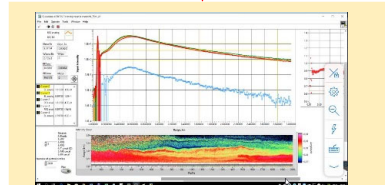
Scanner technology and appl.
(e.g. Späth et al. AMT 2016)



Housing: Ultra-stable, thermally controlled frame and housing



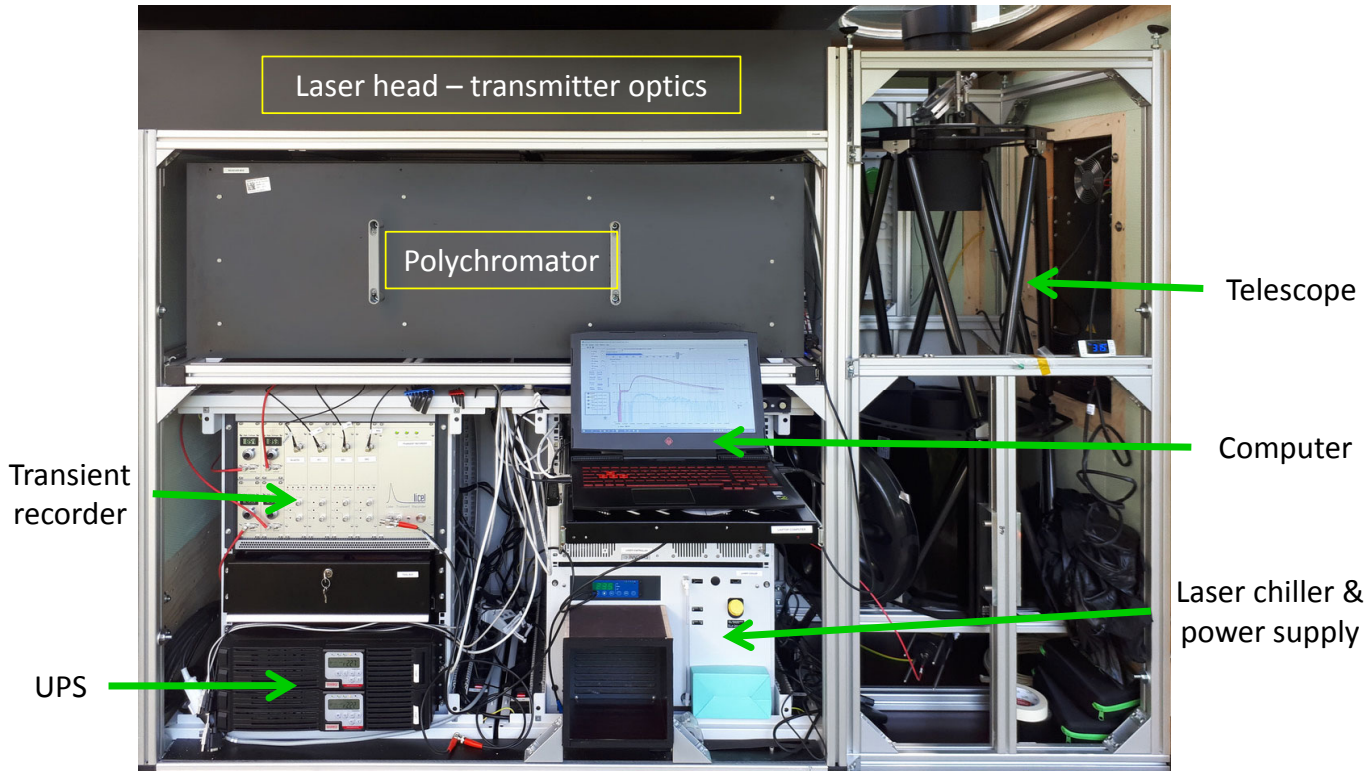
Laser:
High-power, injection-seeded diode-laser
(e.g. Wulfmeyer et al. OE 2000, Ostermeyer et al. AO 2005, Wagner et al. AO 2013)
>100 days operation by now



Real-time data processing with error propagation
(Lenschow et al. 2000, Wulfmeyer et al. JAS 2016)

- Key features:**
- High accuracy and resolution of T and WV profiling day- and nighttime
 - Fulfilling WMO Breakthrough and Goal Requirements for Nowcasting/VSRF in the lower troposphere
 - Compact, operational, and robust
 - Continuous operation with minor laser maintenance for > 3 years
 - Remote control via mobile phone
 - Eye safe

MOSES Raman Lidar: Specifications



Transmitter

- Diode-pumped Nd:YAG laser
- 200 Hz, **20 W** @ 355 nm

Receiver

- **40 cm** primary-mirror telescope
- 4 channels:
Elastic, RR1, RR2 and water vapor

Elastic and Raman channels (Licel GmbH)

- **7.5 m, 1 - 10 s** (raw data)
- Both analog and photon counting mode

Primary Data Products:

- Temperature
- Water vapor mixing ratio
- Relative humidity
- Particle backscatter coefficient @ 355 nm
- Particle extinction coefficient @ 355 nm

Dimensions:

Approx. 2.1m x 2.6m x 1.4m (H x W D)

Weight:

Approx. 900 kg

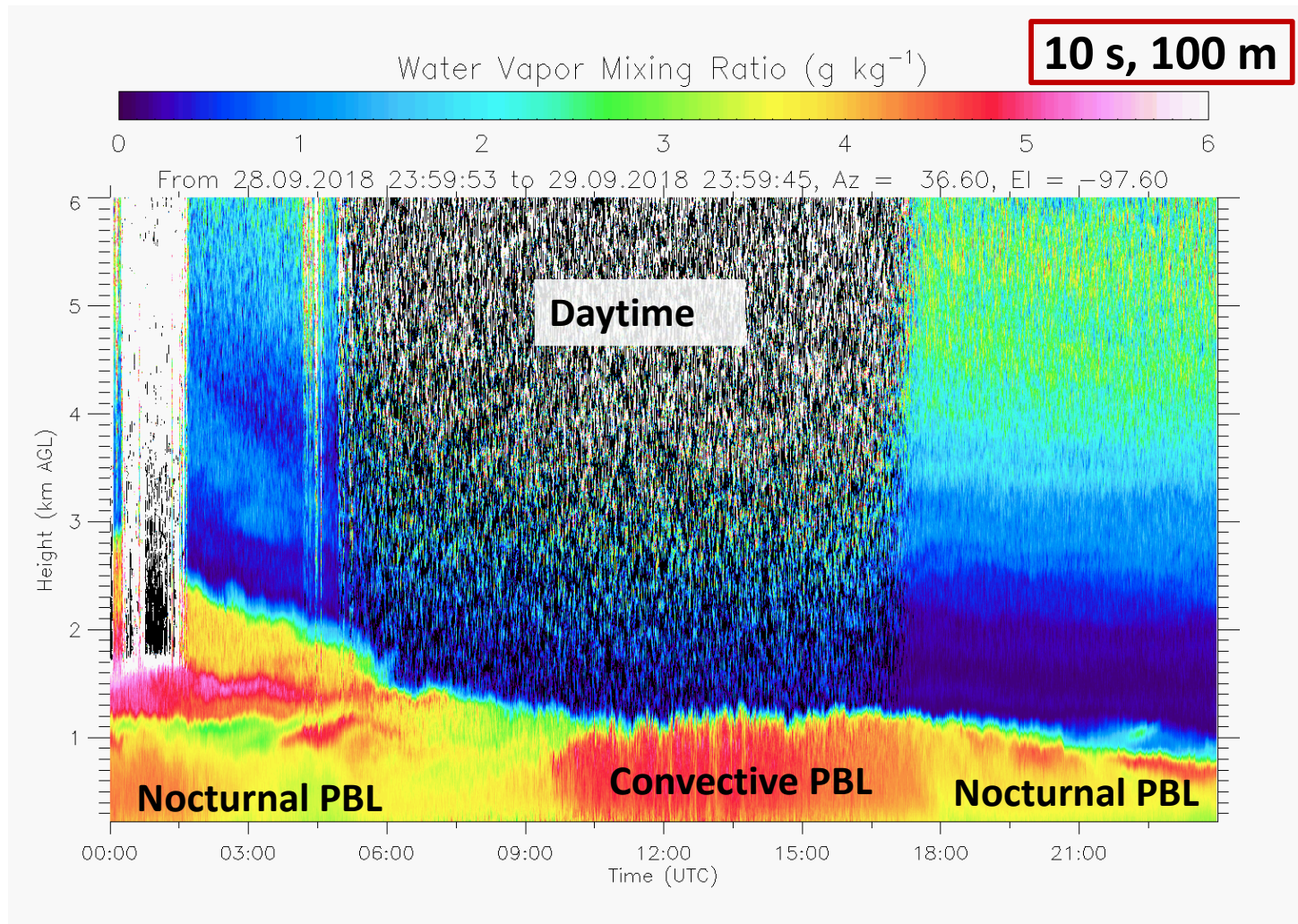
Operation temperature:

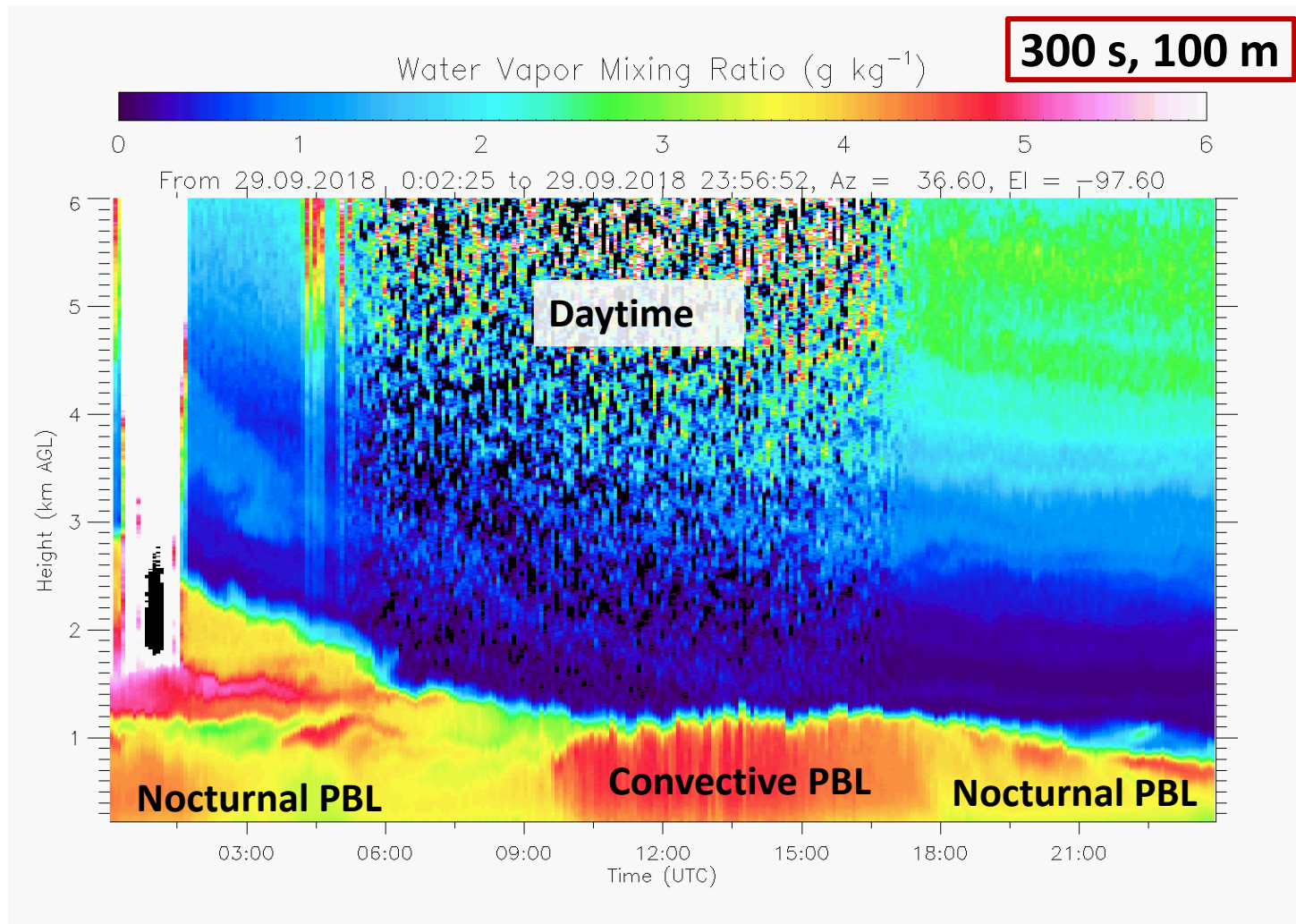
-20°C to 40°C

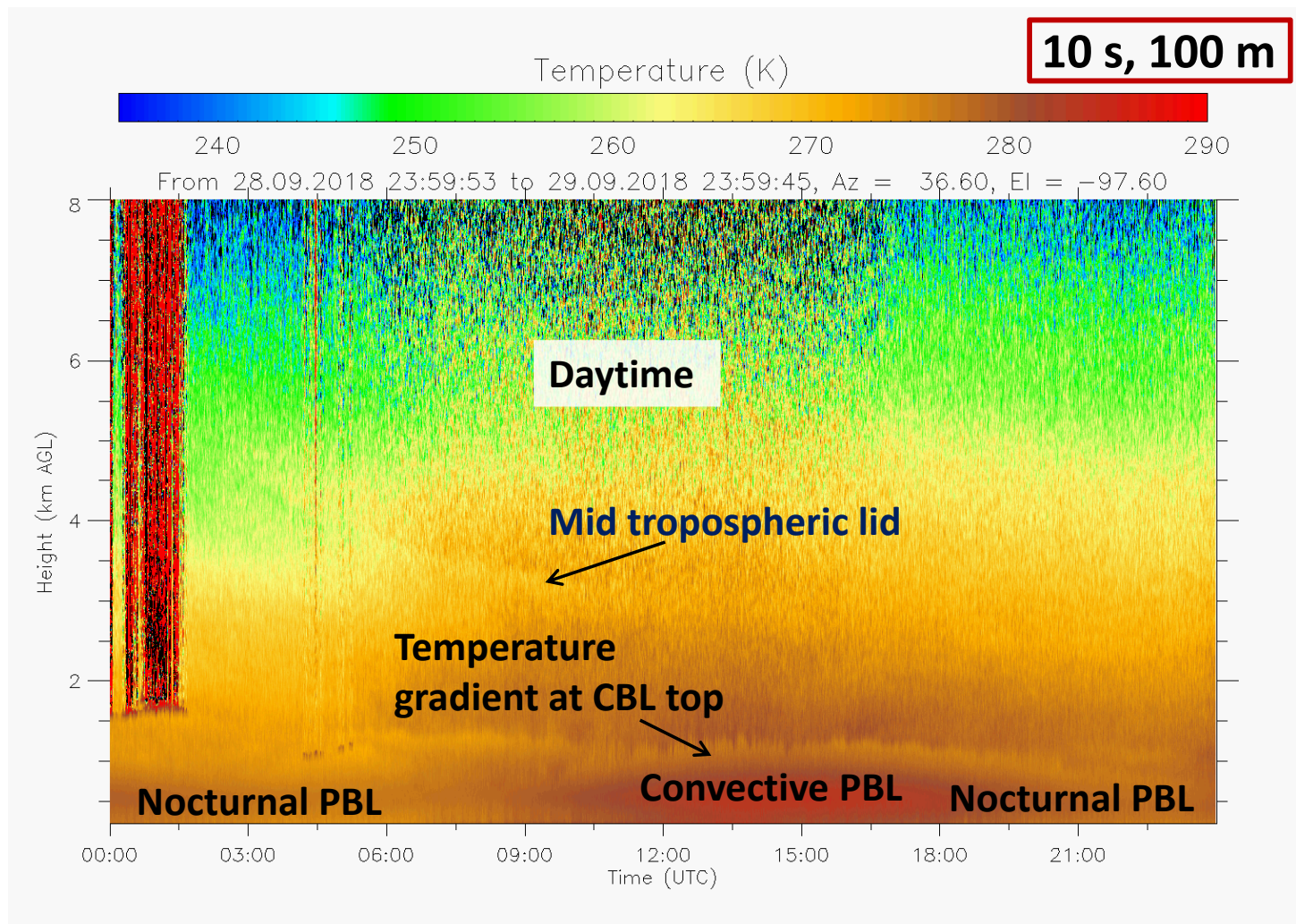
Power consumption:

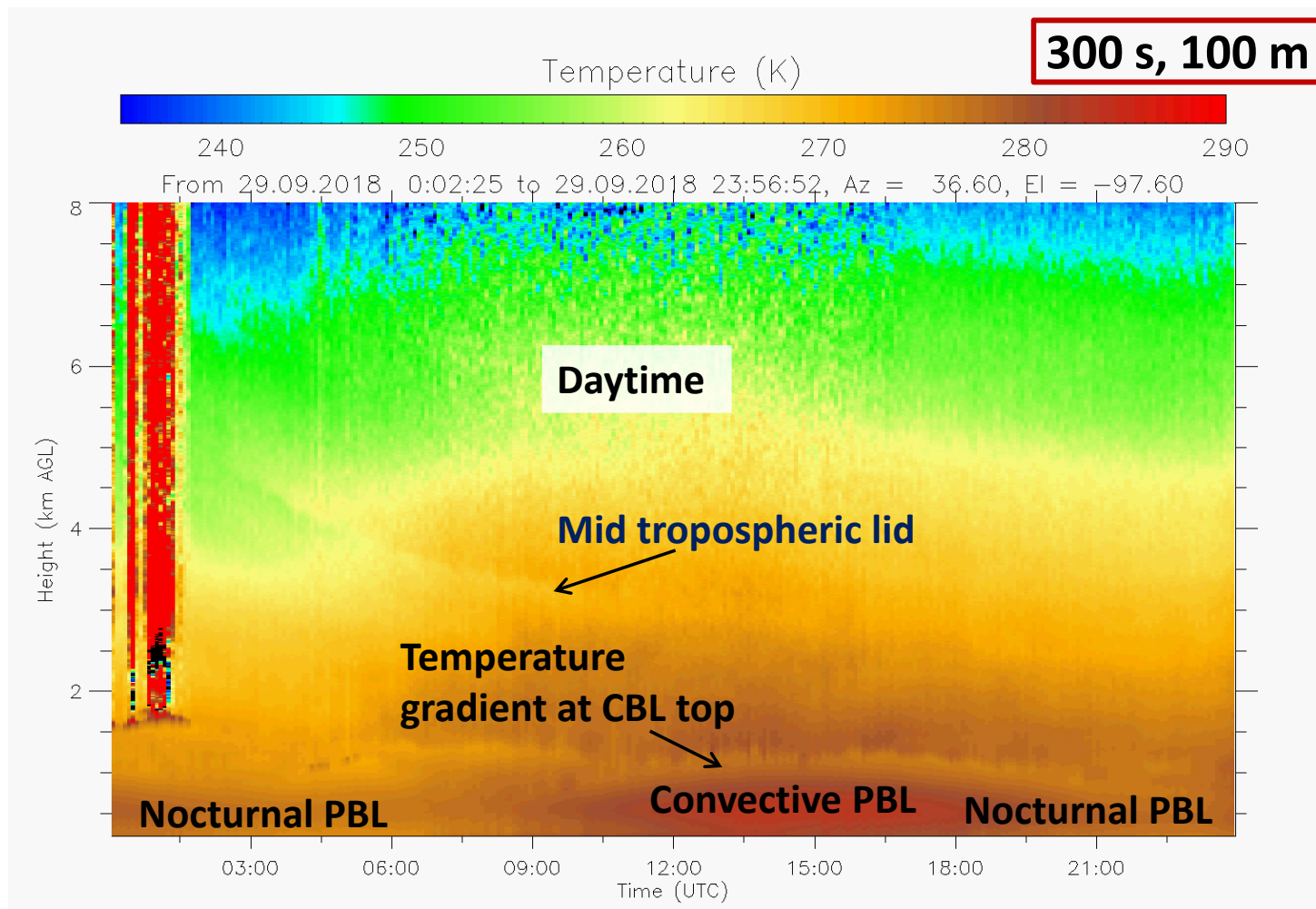
Approx. 5 kW

WVTRL Performance









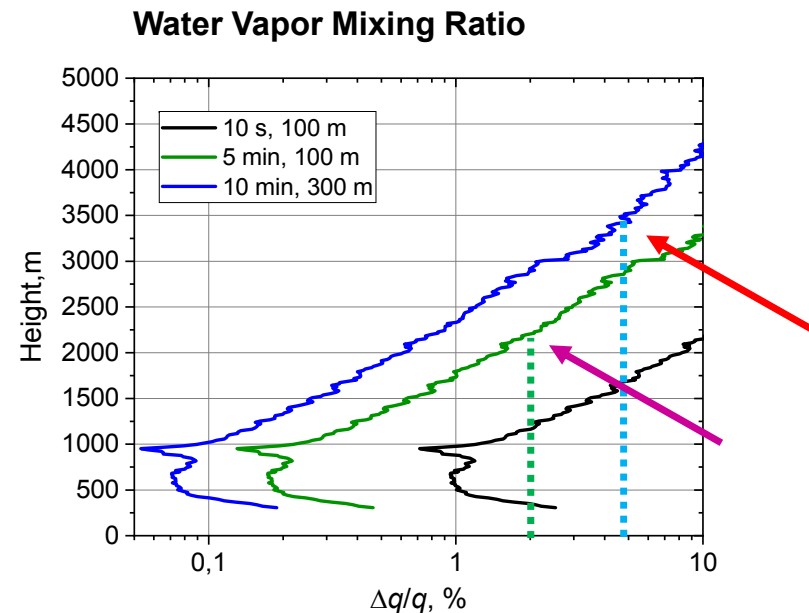
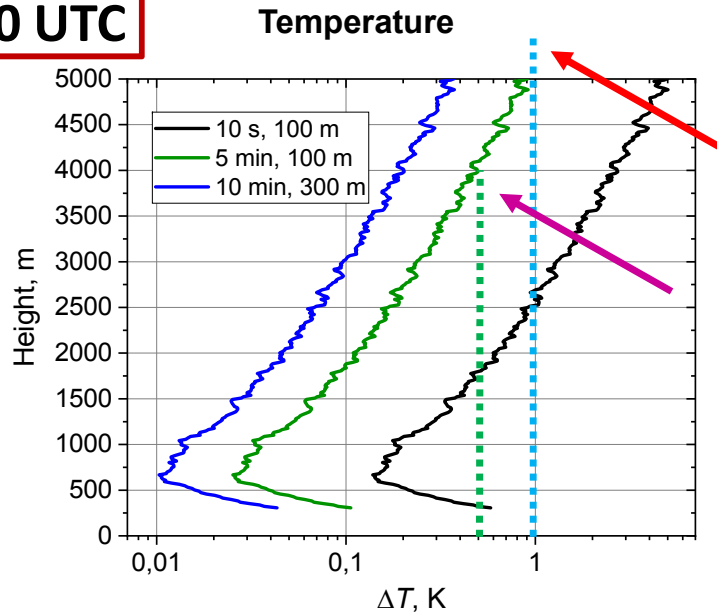
WV and T profiling fully consistent with simulations and WMO requirements.

Raman Lidar: Statistical Uncertainties



01.11.2018
15:00 – 16:00 UTC

Method of *Wulfmeyer et al. JAS 2016*



WMO Requirements for Nowcasting/VSRF in the Lower Troposphere:

“Breakthrough” requirement (10 min, 300 m):	
1 K Fulfilled >> 5 km!	5% Fulfilled up to 3.5 km!
“Goal” requirement (5 min, 100 m):	
0.5 K Fulfilled up to 4 km!	2% Fulfilled up to 2.2 km!

<https://www.wmo-sat.info/oscar-staging/requirements>

Scale-X Campaign – MOSES

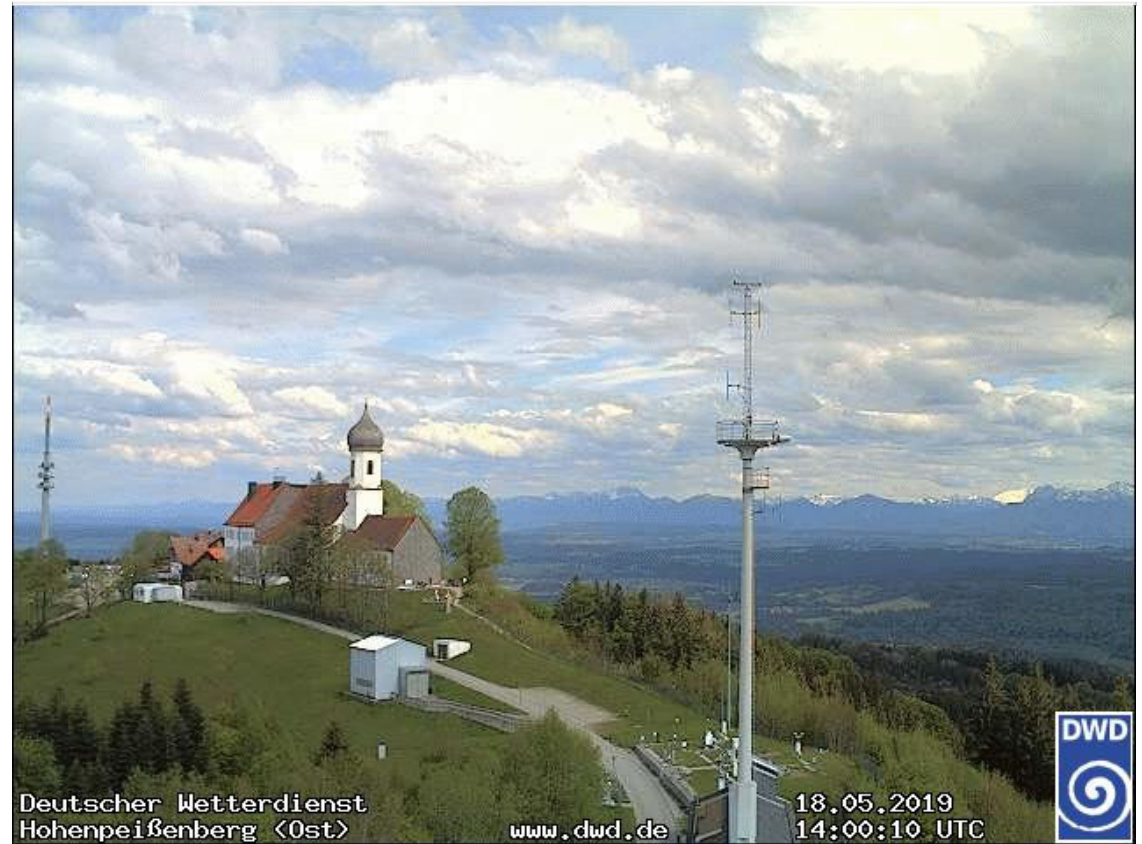


<https://blogs.helmholtz.de/moses/de/>

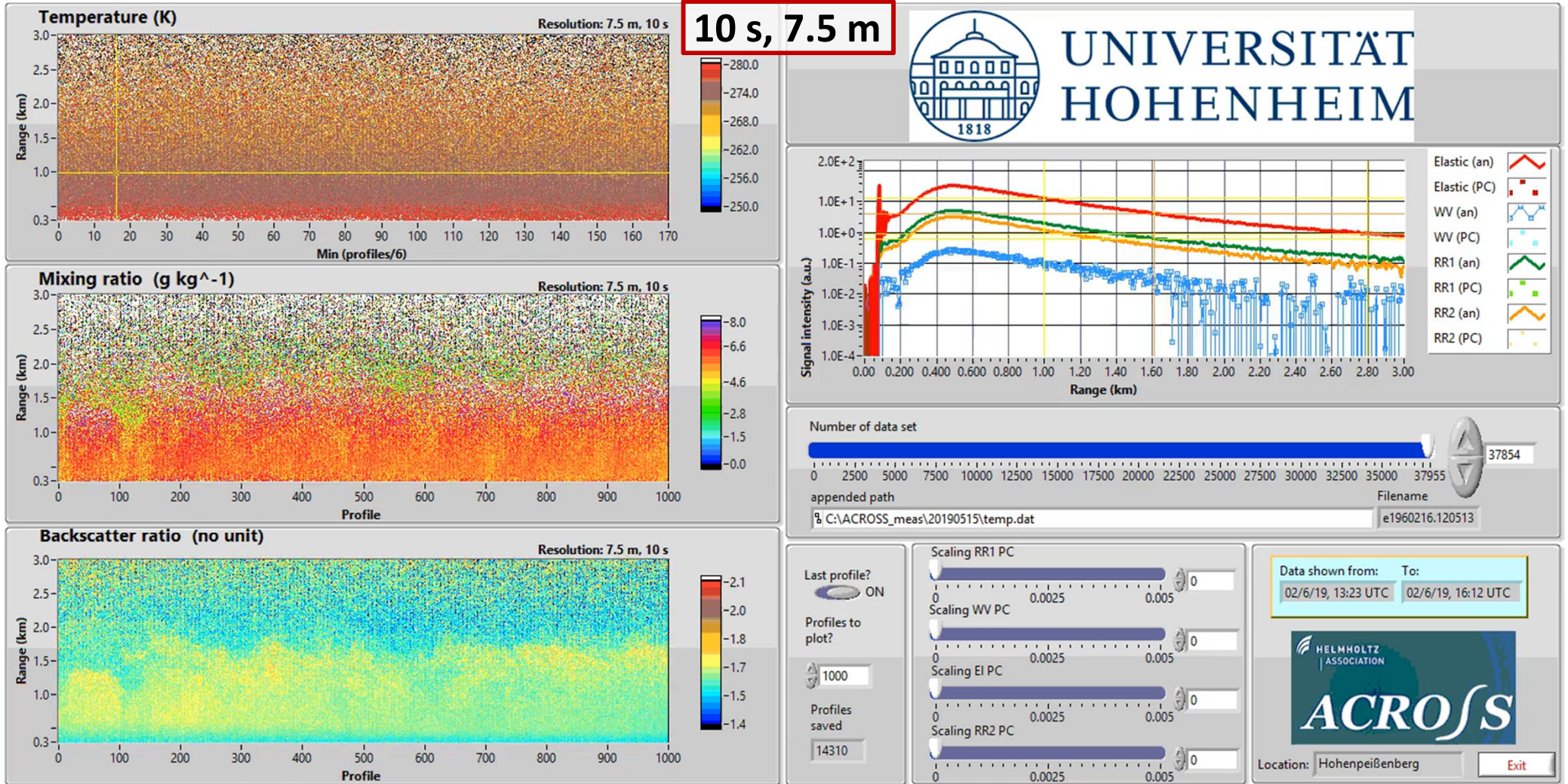
<https://scalex.imk-ifu.kit.edu/#campaigns>



Hohenpeißenberg – Bavaria, Germany



Real-Time Control: LabView Panel



Applications of new WVTRL



- Climate monitoring
- Model verification
- Verification of other observing systems
- Process studies and improvement of model physics:
 - Land-surface exchange
 - PBL turbulence research including entrainment
 - Mesoscale processes such as convection initiation
 - *Aerosol-cloud interaction*
- Nowcasting
- Data assimilation for numerical weather prediction
- Artificial intelligence and machine learning
- Airborne operation, ...

