## Ice Concentration Retrieval in Mixed-phase Stratiform Clouds (MSCs) Using Radar Reflectivity $(Z_e)$ and 1-D Ice Growth Model ASR Damao Zhang<sup>1</sup> (<u>dzhang4@uwyo.edu</u>), Zhien Wang<sup>1</sup>, Andrew Heymsfield<sup>2</sup>, Jiwen Fan<sup>3</sup> nospheric vstem Research <sup>1</sup>University of Wyoming, Laramie, WY; <sup>2</sup> NCAR, Boulder, CO; <sup>3</sup>PNNL, Richland, WA

Abstract: We develop an approach to retrieve the ice number concentration ( $N_{ice}$ ) in MSCs by using  $Z_e$  measurements. A 1-D ice growth model is developed to calculate the ice diffusional growth and corresponding  $Z_{e}$  profile in MSCs. Combining modeled and observed  $Z_{\rho}$  provides  $N_{ice}$  estimations in MSCs with an uncertainty of a factor of 2, statistically.

## **1-D Ice Growth Model and Validations**

Ice particles are initiated at the top of supercooled liquiddominated layer, grow



- large and fall out of the layer.
- Strong temperature dependence of ice growth habits.
- > Only ice diffusional growth is considered.
- $\succ$  Terminal velocity  $(V_t)$ from Heymsfield and Westbrook (2010).
- Adaptive habit evolution method (Harrington et al.,





Fig 2. Ice Mass growth with time from 1-D ice growth model and model and 4 years of MMCR chamber cloud measurements (Takahashi and Fukuta 1991, with different signs). and 75% of data.

**Fig 3**.  $Z_{e_n}$  from 1-D ice growth measurements of MSCs at NSA Barrow. Red boxes: 25%, 50%,

Fig 4. Same as Fig 3, except for Doppler velocity comparisons.

N ice from retrieval (/L)

 $Z_{e_{layer}}$  (dBZ)



## **N\_ice** estimation and Validations

➢ In similar MSCs in terms of same CTT and LWP:  $Z_e(dBZ) = 10\log 10(N_ice^*Z_{nor})$  $Z_{nor}$  is the radar reflectivity  $(mm^{6}/m^{3})$  for normalized ice crystal size distribution.

- $\succ N_{ice}$  is the main cause for  $Z_{\rho}$  difference among similar MSCs (Zhang et al., 2012).



The retrieved *N\_ice* are within an uncertainty of a factor of 2 compared with *in situ* measurements, statistically.



 $\succ Z_{e \ laver}$ : mean  $Z_{e}$  between cloud top and 500 m below.





Fig 7. Same as for Fig 6, **Fig 6**. Dec 10<sup>th</sup>, 2007 during ICEexcept for the case on Apr 8<sup>th</sup>, L. a) lidar backscattering; b) radar 2008 during ISDAC. Z<sub>o</sub> profiles; c) in situ 2D-C N\_ice Vs.  $Z_{e \ laver}$ , ; **d**)  $N_{ice}$  from in situ 2D-C and retrieval.

## References

-18 -16 -14 -12 -10 -8

WCR Z<sub>e laver</sub> (dBZ)

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Harrington, J. Y., et al., (2013), A Method for Adaptive Habit Prediction in Bulk Microphysical Models. Part II: Parcel Model Corroboration, J. Atmos. Sci., 70(2).