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Introduction

A unique, real-time Cloud Optical Depth (COD) sensor, dubbed the Three-Waveband Spectrally-agile Technique (TWST), has been developed and successfully deployed to serve as a ground-based, portable and reliable means for remote cloud monitoring. It uses the spectral radiance of scattered sunshine from a small area of overhead cloud and the MODTRAN5 model of atmospheric radiation transport to determine Cloud Optical Depths. A real-time output assists with monitoring dynamic situations, and continuous data logging permits detailed post processing. The underlying phenomenology of TWST is similar to that employed in AERONET sensors running in cloud-mode [1,2,3,4] which provided direct validation of TWST during simultaneous TWST-AERONET data collections at the AERONET site in Harvard Forest, Petersham MA.

Akin to, but Differentiated from AERONET Cloud Mode

Unlike AERONET, TWST is a dedicated, continuous cloud sensor with the ability to work in vegetated and non-vegetated terrains, in addition to being portable rather than a fixed installation like AERONET. Although the TWST concept is strongly grounded in the NASA AERONET Cloud Mode approach [2,3], the requirements driving the TWST sensor design demanded a substantial extension beyond the capabilities provided by the basic AERONET Cloud Mode. These requirements included:

-Need for a continuously-updated, real-time COD output;

-Fast, providing updates of COD at rates up to 1 per sec;

-Field-worthy – reliable, rugged and accurate;

-Portable - easy to set up and operate under field conditions; -Spectrally-agile in response to the changing earth albedo by location and by season.

Equivalent Width Distinguishes Thin vs Thick Clouds

An underlying problem in inferring optical depth from solarscattered radiance measurements is that the down-welling cloud radiance is a two-valued function of the COD [Fig 1]. TWST uses the O_2 A-band Equivalent Width as the means to overcome this ambiguity. This band, centered at 761 nm, is not badly overlapped by other absorbers such as H₂O, and unlike water vapor, O_2 concentrations in the atmosphere are quite stable. The Equivalent Width of the O_2 band depends on the total photon path length and increases with more scattering events thereby distinguishing thin from thick clouds.

Fig 1. Zenith Radiance versus COD



A Real-Time Cloud Optical Depth Sensor Three-Waveband Spectrally-agile Technique (TWST)

Methods TWST uses the brightness of visible and Near Infra-Red (NIR) sunlight scattered off a small region of cloud directly overhead to determine the COD. MODTRAN is used to pre-compute a table of COD versus spectral radiances as a function of solar zenith angle. Fig 2. Cloud Multiple Scatter Model Solar Zenith Absorption Scattering Liquid Water Coefficient Atmospheric Model Coefficient Column Depth $\sigma_{ext} = \sigma_{sc} + \sigma_{ab}$ $LWCD = \int n_{lw}(z)dz$ Depth Cloud Type \Rightarrow Phase Function $COD = \int \sigma_{ext} n_{lw}(z) dz$ **(a)** Fxtinction Clouc Base Altitude Coefficient Optical Depth Sensor Vis Wavebands Albedo 1D Plane Parallel Cloud - DIScrete Ordinate Radiative Transport Table 1. TWST COD Sensor Specifications Weight 20 lbs Power 5 hour battery life, or continuous with AC power source for control computer **(b)** Size 11" x 8" x 8" plus 8" external sun baffle; or 11" x 11" x 8" with internal sun baffle Operating COD Range Blue Sky to Cloud OD 100 Cloud OD Precision 1% (typical, depends on update rate) Cloud OD Accuracy 5 % (typical) Electrical Power + Data One USB connection to computer Container NEMA 4 sealed enclosure Data Logging Rate 1 Hz (typical), variable sampling interval from 0.1 to 120 seconds Spectral Range 350 – 1000 nm Spectral Bands used in Cloud OD retrieval 440, 761, and 870 nm (typical) Fig 3. Harvard Forest AERONET Site with **TWST Collecting Data Simultaneously** (C) (C) AERONET

TWST



