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MOTIVATION AND GOALS

Parameters that control ice particle characteristics (e.g., concentrations, masses, shapes, densities, fall speeds, aspect ratios, scattering) are usually specified as constants in models. Observations show large variability of these parameters over scales smaller than typical model domain sizes, and significant correlation in the variability of parameters. The effects of this parameter variability on simulated cloud and precipitation properties are essentially unknown. ARM field campaign observations are being used to characterize this parameter variability, and develop an observationally constrained stochastic microphysical framework that can account for it. By running simulations of well-observed field campaign cases that employ this new framework, project goals include:

- 1) quantifying impacts of including ice microphysical parameter variability on deep convective cloud and precipitation processes,
- 2) characterizing the spread of ensemble solutions generated from different realizations applying the stochastic scheme, with practical implications for ensemble weather and climate prediction,
- 3) identifying specific parameters that cause the greatest impacts on cloud and precipitation properties when varied, thereby motivating a focus on measuring of these parameters in future field campaigns, and
- 4) assessing potential improvement and causes for improvement of simulated cloud properties using stochastic ice parameters through comparison of model output with field campaign observations.

STOCHASTIC FRAMEWORK

A parameterization framework has been developed that incorporates stochastically-varying microphysical parameters. This has been implemented into the 1 ice category version of the Predicted Particle Properties microphysics scheme (P3, Morrison and Milbrandt 2015) within the Weather Research and Forecasting model (WRF).

We initially focus on varying the "a" and "b" mass (m)-size (D) relationship parameters for unrimed and partially-rimed ice, given by $m = aD^b$.

THE METHOD:

1. Sample b and density $\rho_{i(500 \mu m)}$ at a reference size ($D_f = 500 \mu m$) as random Gaussian-distributed variables at each grid location and across several time steps. b has a mean of 2.1 and standard deviation of 0.32. Based on initial aircraft observations analysis, $\rho_{i(500 \ \mu m)}$ has a mean of 100 kg m⁻³ and standard deviation of 32 kg m⁻³. b and $\rho_{i(500 \ \mu m)}$ are assumed to be uncorrelated, which is reasonable based on the observational analysis.

2. Apply a running mean filter to generate spatially and temporally autocorrelated b and $\rho_{i(500 \mu m)}$. The filter has a width in the time, horizontal, and vertical dimensions of τ_t , τ_h , and τ_v , respectively. "Ghost" points are added outside of the domain and prior to the initial time to ensure a consistent number of points are included for all grid locations and time steps when applying the running mean filter.

3. Multiply the sampled b and $\rho_{i(500 \ \mu m)}$ by constant coefficients to ensure that the variance equals the original variance before applying the running mean filter.

4. Calculate *a* from $a = \rho_{i(500 \text{ µm})} \pi D_f^3 / (6D_f^b)$.

REFERENCES: Morrison, H., and J.A. Milbrandt, 2015: Parameterization of cloud microphysics based on the prediction of bulk ice particle properties. Part I: Scheme description and idealized tests. J. Atmos. Sci., 72, 287-311.

Development and Testing of a Stochastic Representation of Ice Microphysical Properties in WRF

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