

## Machine Learning for the ARM Climate Research Facility

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#### Outline



#### CIMEL Sun Photometer Instrument Anomaly Detection

- Random Forest
- MFRSR Instrument Anomaly Detection
  - Multivariate
    Regression
- AOS Local Source Emission Identification
  - Neural Network
  - Support Vector Machine





#### **CIMEL Sun Photometer Instrument Anomaly Detection**



- The CIMEL Sun Photometer is a multi-channel automatic sun and sky scanning radiometer that measures the direct solar irradiance and sky radiance at the Earth's surface.
- The sampling rate is typically 10 minutes.
- Measurements are taken only in daylight hours without precipitation. The measurements are sensitive to cloud conditions.
- THE PROJECT: Apply machine learning algorithms to detect anomalies due to instrument failure modes with a fast, automated application. Failure modes include obstructions and filter degradation.







- A machine learning model considers inputs from multiple data features simultaneously.
- There are large variations due to weather conditions in a given day, so features are extracted on a daily basis.
- Example features include the coefficients of daily fits (A<sub>0</sub>, A<sub>1</sub>, A<sub>2</sub>) of the aerosol optical depth (AOD) measurements for each filter to the curve:

 $AOD(t) = A_0 + A_1t + A_2\cos(\Theta(t))$ 



An example of fits to the data for one day. Points marked by an "x" are influenced by clouds and not included in the fit.

## The Cosine Coefficient Features for the CIMEL Sun Photometer



- Almost 3 years of data are processed from the SGP site in Oklahoma (4/1/14 – 2/12/17).
- Shown here is the cosine coefficient for each day from the instrument's 8 filters.
- The arrows point to days where a spider web was obstructing the measurements.
- Correlating multiple features can be more sensitive to problems then considering single features.





### Anomaly Detection Using a Random Forest Regressor



- A random forest model is an ensemble method that builds a set of decision trees from subsets of data and subsets of features. The final result is the average of the results from all of the trees.
- A random forest model is chosen for the following reasons:
  - It generalizes well.
  - The input data does not need to be scaled or processed.
  - Results are easy to interpret and provide information on the nature of the problem.



For the CIMEL sun photometer, the random forest is asked to predict the value of a reference measurement, the AOD value at noon for the 500 nm channel.



## **CIMEL Sun Photometer Anomaly Detection Results**



- A training set covering a period of "good" instrument operation is defined.
- The model is trained using that dataset. It learns the features of the data.
- The trained model is asked to predict the rest of the data. The residual root mean square (RMSE) is reported.
- High RMSE values indicate anomalous days.
- The model translates well to other sites with little tuning.



The application detected all known problems with the instrument over this period. Running time = 15 seconds per year of data.

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## Multifilter Rotating Shadow-band Radiometer (MFRSR) Anomaly Detection



- The MFRSR takes spectral measurements of direct normal, diffuse horizontal, and total horizontal solar irradiances.
- The sampling rate is 20 seconds.
- Measurements are taken in daylight hours and are affected by clouds.
- A machine learning application similar to that for the CIMEL sun photometer has been developed.
- The application also contains a filter algorithm to detect a common problem due to misalignment of the shadow band.





# **Detecting Shadow Band Misalignment in the MFRSR**



This problem mode creates an oscillating pattern in the data.

A Fast Fourier Transform (FFT) has been shown to be effective to detect this (*M.D. Alexandrov et al., Applied Optics 46,* 8027 (2007)).

The FFT algorithm is automated here. One year of data can be analyzed in 2 minutes.

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## MFRSR Shadow Band Misalignment Detection Results



- This shows the output of the FFT algorithm per day from the E33 instrument at the SGP site over one year.
- There is a DQR documenting a misalignment problem covering the red shaded area.
- The FFT algorithm successfully identifies the problem. There are no false positives reported for this year.





#### **MFRSR Anomaly Detection Results**



- A multivariate regression model is trained to predict the diffuse narrowband irradiance for filter 1.
- The model is trained on 3 months of nominal operation.
- The model is then compared to the data in the test set and the RMSE is reported.
- A sensor problem in one channel that was reported in a DQR is successfully detected.





#### **Identifying Local Emission Sources in the Aerosol Observing System (AOS)**





THE PROJECT: AOS instruments at the ENA site are located next to an airport. Develop an automatic machine learning application to identify emissions from the airport using multiple AOS instruments.





## A Neural Network to Identify Airplanes in Tower Camera Images



- For supervised machine learning, the data must be tagged before training.
- Tower camera images of the tarmac are used to tag local emission sources.
- A neural network was developed to automatically identify airplanes in the images.
- Once trained, the neural network can process a day of images (700 of them) in 10 seconds on a laptop.
- The accuracy per image for airplane identification is 96%.







## **Local Emission Sources in the AOS Data**

- This shows 5 simultaneous data streams from 4 different instruments over one day:
  - CO Monitor Carbon monoxide concentration
  - Greenhouse Gas Monitor Carbon dioxide concentration
  - Ultra-high Sensitivity Aerosol Spectrometer (UHSAS) mean particle size
  - UHSAS particle count integral
  - Condensation Particle Counter aerosol concentration
- Most instruments have a sampling rate of 1 second. The UHSAS has a sampling rate of 10 seconds This is more than 8000 measurements per day per data stream.
- Notice that not all events are seen in all data streams. Multiple instruments are necessary.





## AOS Local Emission Source Detection Results





A 2-D illustration of an SVM model. A hyperplane (red line) is constructed to maximize the class separation. The yellow \_\_\_\_\_points are the support vectors.

- A training data set is defined over 5 days of AOS operation by removing data corresponding to times when local emission sources are present as identified by the neural network.
- A one-class Support Vector Machine (SVM) model is trained. The SVM defines a single class describing good data.
- The model is then compared to data in the test set. The model will report data that lies outside of it's class as anomalies.
- The model is better than 99% accurate for identifying local emission sources.
- Running time for 1 day of data: 15 seconds

Results from the SVM model over one day of AOS data (11/21/16). Events from fire trucks and two airplanes are correctly identified (red dots). The yellow dots represent falsely reported anomalies.





#### Summary



- Machine learning algorithms have been applied to anomaly and local source emission detection in several ARM instruments.
- The algorithms are powerful because they can make inferences based upon multiple measurements from multiple instruments simultaneously.
- A fast and accurate assessment of data quality has been demonstrated and can be interpreted at a glance.
- Further evaluation and implementation of the applications is underway.
- Many exciting ARM analyses are possible with the power of machine learning!

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- More details can be found in the following posters:
  - ► A2 Poster #101 (AOS) and B2 Poster # 136 (CIMEL Sun Photometer)

